

Rational parametrizations in differential algebra

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MAX PLANCK INSTITUTE
FOR MATHEMATICS IN THE SCIENCES



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The solutions $y(t)$ of the ODE-system

$$\Sigma = \begin{cases} x_1'(t) = x_2(t)^2, \\ x_2'(t) = x_1(t) u(t), \\ y(t) = x_2(t) \end{cases}$$

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Question

- 1 How to transform Σ into F and conversely, F into Σ ?
- 2 Is this always possible? Under which assumptions for Σ (polynomiality, real coefficients etc.)?

Rational parametrizations $\mathcal{S} \rightarrow P$

Let $\mathcal{S} \subset K[y_0, \dots, y_n]$ be a finite set of polynomials (over a field K with characteristic zero). We call

$$\mathbb{V}(\mathcal{S}) := \{P \in \overline{K}^{n+1} \mid \forall F \in \mathcal{S} : F(P) = 0\}$$

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- 1 $P = (x^3, x^2)$ is a parametrization of the cusp $\mathbb{V}(y_0^2 - y_1^3)$.
- 2 The unit sphere $\mathbb{V}(y_0^2 + y_1^2 + y_2^2 - 1)$ has the parametrization

$$P = \left(\frac{2x_1}{x_1^2 + x_2^2 + 1}, \frac{2x_2}{x_1^2 + x_2^2 + 1}, \frac{x_1^2 + x_2^2 - 1}{x_1^2 + x_2^2 + 1} \right).$$

Characterization theorem

Let $F \in K[y_0, y_1]$. $\mathbb{V}(F)$ admits a rational parametrization iff the **genus** of $\mathbb{V}(F)$ is **zero**.

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- 2 Rational parametrizations of curves and surfaces can always be chosen **birationally**. As a consequence, all such rational parametrizations P, Q can be related by reparametrizations $P(x) = Q(s(x))$ with $s \in \overline{K}(x_1, \dots, x_m)^m$ and invertible $\mathcal{J}(s)$, $m \in \{1, 2\}$.

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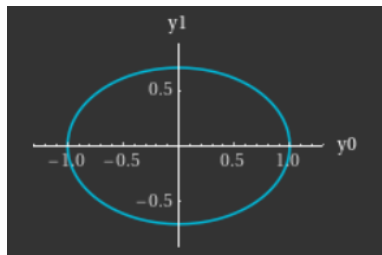
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- 3 Rational parametrizations of curves $P \in L(x)^2$ can be found over **optimal fields**, i.e., with coefficients in a minimal field extension $K \subseteq L \subset \overline{K}$. In fact, $[L : K] \leq 2$.

Example 1

Let $F = y_0^2 + 2y_1^2 - 1$. Then $\mathbb{V}(F)$ admits the birational parametrization

$$P = \left(\frac{1-x^2}{1+x^2}, \frac{\sqrt{2}x}{1+x^2} \right)$$

over the optimal field of parametrization $\mathbb{Q}(\sqrt{2})$.



Given $P = \left(\frac{p_0}{q}, \dots, \frac{p_n}{q} \right) \in \overline{K}(x_1, \dots, x_m)^{n+1}$, we can always find a system of algebraic polynomials \mathcal{S} such that P is a rational parametrization of $\mathbb{V}(\mathcal{S})$:

Implicitization $\mathcal{S} \leftarrow P$

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$$\langle y_0 q - p_0, \dots, y_n q - p_n, qz - 1 \rangle \cap \overline{K}[y_0, \dots, y_n]$$

and the finite number of generators can be chosen as \mathcal{S} .

Example 1

From $P = \left(\frac{1-x^2}{1+x^2}, \frac{\sqrt{2}x}{1+x^2} \right)$ we get the ideal generated by

$$(1+x^2)y_0 - (1-x^2), (1+x^2)y_1 - \sqrt{2}x, (1+x^2)z - 1.$$

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Its Groebner basis (w.r.t. $z > x > y_0 > y_1$) is

$$\mathcal{G} = \{y_0^2 + 2y_1^2 - 1, -\sqrt{2}xy_1 - y_0 + 1, -xy_0 - x + \sqrt{2}y_1, y_0 - 2z + 1\}$$

such that $F = y_0^2 + 2y_1^2 - 1$ is the only element in $\mathcal{G} \cap \overline{\mathbb{Q}}[y_0, y_1]$.

Do we have counterparts of the previous concepts in differential algebra?

- 1 Parametrizations / Implicitization
- 2 Birationality
- 3 Optimal coefficient fields and computation with parameters
- 4 Is it algorithmic?

Let us consider ODE models of the form

$$\Sigma = \begin{cases} \mathbf{x}' = \mathbf{f}(\mathbf{u}, \mathbf{x}), \\ \mathbf{y} = \mathbf{g}(\mathbf{u}, \mathbf{x}) \end{cases} \quad (1)$$

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with the components of \mathbf{f}, \mathbf{g} in $\overline{K}(\mathbf{u}, \mathbf{x})$. We define the (prime) **differential ideal of Σ** as

$$I_{\Sigma} = [q\mathbf{x}' - q\mathbf{f}, q\mathbf{y} - q\mathbf{g}] : q^{\infty} \subset \overline{K}[\mathbf{x}^{(\infty)}, \mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}],$$

where q is the common denominator of \mathbf{f} and \mathbf{g} , and

$$I : a^{\infty} = \left\{ r \in R \mid \exists \ell : a^{\ell} r \in I \right\}.$$

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Important facts

- 1 The result is a finite number of (reduced) **triangular sets** with one essential component \mathcal{G} .
- 2 The **general solution** of \mathcal{G} and that of I_Σ coincides.
- 3 Using the ordering $y'_i, u'_i < x'_i$, the **intersection ideal** $I_\Sigma \cap \overline{K}[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$ is generated by $\mathcal{G} \cap \overline{K}[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$.

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Implicitization

$\mathcal{S} = \mathcal{G} \cap \overline{K}[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$ are called the **IO-equations** corresponding to Σ .

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Consider

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Then $y' = -3x^2 \cdot \frac{x^2-1}{3x^2} = -x^2 + 1$ and

$$\text{Res}_x(y - x^3, y' + x^2 - 1) = y'^3 + y^2 - 3y'^2 + 3y' - 1$$

is the IO-equation of Σ .

Given $\mathcal{S} \subset K[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$, one can ask the question whether there is a system Σ as in (1) such that \mathcal{S} are the IO-equations of Σ . In the affirmative case, Σ is called a **realization** of \mathcal{S} .

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Finding a realization is similar to the problem of finding a rational parametrizations of a given set algebraic set.

Algebraic-geometric approach

Given $\mathcal{S} \subset K[y^{(\infty)}, u^{(\infty)}]$, we now forget about the differential relations and consider $y^{(i)}(t) =: y_i$ as independent variables.

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Parametrization

If \mathcal{S} has a realization $\Sigma = \begin{cases} \mathbf{x}' = \mathbf{f}(u, \mathbf{x}), \\ y = g(u, \mathbf{x}), \end{cases}$ then

$$P = (g, \mathcal{L}_{\mathbf{f}}(g), \dots, \mathcal{L}_{\mathbf{f}}^n(g)), \quad (2)$$

where $D_u(h) = \sum_{j \geq 0} u^{(j+1)} \cdot \partial_{u^{(j)}} h$ and $\mathcal{L}_{\mathbf{f}}(h) = \sum_{i=1}^n f_i \partial_{x_i} h + D_u(h)$ is the Lie-derivative of h w.r.t. \mathbf{f} , defines a **rational parametrization** of $\mathbb{V}(\mathcal{S})$.

Necessary condition

A necessary condition for the existence of a realization of \mathcal{S} is that $\mathbb{V}(\mathcal{S})$ admits a **rational parametrization**.

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Assume that $\mathbb{V}(\mathcal{S})$ with $\mathcal{S} \subset \overline{K}[y, \dots, y^{(n)}, u^{(\infty)}]$ admits a rational parametrization $P = (P_0, \dots, P_n) \in \overline{K}(u^{(\infty)})(\mathbf{x})^{n+1}$. Then we seek for a reparametrization $P(\mathbf{x}(\mathbf{t}))$ that additionally fulfills the differential relations

$$\mathcal{J}(P_0, \dots, P_{n-1}) \cdot \mathbf{x}' = (P_1 - D_u(P_0), \dots, P_n - D_u(P_{n-1})). \quad (3)$$

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Correspondence theorem

\mathcal{S} has a realization iff $\mathbb{V}(\mathcal{S})$ has a rational parametrization such that (3) is independent of derivatives of u .

Important facts

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- 2 For a realization $\Sigma = \{\mathbf{x}' = \mathbf{f}(u, \mathbf{x}), y = g(u, \mathbf{x})\}$ and some $\mathbf{s} \in \overline{K}(\mathbf{x})^m$ with invertible Jacobi-matrix,

$$\mathbf{x}' = \mathcal{J}(\mathbf{s}(\mathbf{x}))^{-1} \cdot \mathbf{f}(u, \mathbf{s}), y = g(u, \mathbf{s}) \quad (4)$$

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The case when $P = (g, \mathcal{L}_f(g), \dots)$ is a birational parametrizations corresponds to the case when \mathbf{x} is “globally **observable**” (important property in control theory).

Observability \leftrightarrow Birationality

Let $F \in \overline{K}[u, u', y, y']$ be realizable. Then there is an **observable** realization of F .

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Real realizations

Let $F \in \mathbb{R}[u, u', y, y']$ be realizable with $\{x' = f(x, u), y = g(x, u)\}$ (over \mathbb{C}). Then there is a **real realization** of F iff there is a reparametrization $s \in \mathbb{C}(x)$ of $P = (f, \mathcal{L}_f(g))$ with $P(s) \in \mathbb{R}(u, u')(x)^2$.

Polynomial realizations

Let $F \in \overline{K}[u, u', y, y']$ be realizable with $\{x' = f(u, x), y = g(u, x)\}$. Then there is a **polynomial realization** of F iff

- u does not effectively occur in any denominator of f or g ; and
- the common denominator q of the coefficients of g , seen as polynomial in u , is of the form $a \cdot (x - b)^m$ for some $a, b \in \overline{K}$ with m greater or equal to the degrees of the numerators of f, g ; and
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All these results are **algorithmic** and can be extended to the case of higher-dimensional corresponding algebraic sets $\mathbb{V}(S)$ as sufficient conditions.

Example 3

Let us consider the non-observable realization

$$\{x' = \frac{1-x}{2u}, y = \frac{(1-x)^4}{u^2+(1-x)^6}$$

corresponding to the rational parametrization

$$P = \left(\frac{(1-x)^4}{u^2+(1-x)^6}, \frac{-(4u^2(1-x)^3+2(1-x)^9+(u^2+(1-x)^6)uu')(1-x)^4}{(u^2+(1-x)^6)^3} \right).$$

We can choose the (algebraic) reparametrization $s := 1 + \sqrt{1-x}$ which leads to the realization

$$\{x' = \frac{1-x}{u}, y = \frac{(1-x)^2}{u^2+(1-x)^3}.$$

Systems involving parameters

In a lot of applications there occur **parameters** that will be estimated from time-series data such as in the following commonly used SEIR epidemic model

$$\Sigma = \begin{cases} S'(t) = -\frac{bS(t)I(t)}{n}, \\ E'(t) = \frac{bS(t)I(t)}{n} - \nu E(t), \\ I'(t) = \nu E(t) - aI(t), \\ y_1(t) = I(t), \\ y_2(t) = n \end{cases} \quad (5)$$

with the coefficient field $K = \mathbb{C}(a, b, \nu, n)$.

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Question

- 1 Is (5) a good model for estimating parameters?
- 2 If not, do we find an equivalent, better, model?

Identifiable parameters (informal)

Consider the ODE system Σ (over $\mathbb{C}(\mathbf{c})$) as in (1). Assume that $\mathbf{x}(0), \mathbf{x}'(0), \mathbf{u}(0) \rightarrow \mathbf{y}(0)$ (maybe even $\mathbf{x}''(0), \dots, \mathbf{u}'(0), \dots, \mathbf{y}'(0), \dots$) are known.

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- If c_i is **uniquely** given from the resulting equations, then c_i is called a **(globally) identifiable parameter**.
- If c_i can have infinitely many values, it is called **non-identifiable**.
- Otherwise, c_i is called **locally identifiable** and can obtain finitely many values given by a polynomial function.

Identifiable functions

The smallest field $\mathbb{C} \subset \mathbb{K} \subset \mathbb{C}(\mathbf{c})$ such that $I_\Sigma \cap \mathbb{C}(\mathbf{c})[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$ is generated as an ideal by $I_\Sigma \cap \mathbb{K}[\mathbf{y}^{(\infty)}, \mathbf{u}^{(\infty)}]$ is called the **field of identifiable functions** of Σ . $h \in \mathbb{C}(\mathbf{c})$ is called **identifiable** if $h \in \mathbb{K}$ and **locally identifiable** if $h \in \overline{\mathbb{K}}$.

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Rule of thumb

The identifiable functions are the rational expressions generated by the **coefficients** of the **IO-equations**.

The **identifiable parameters** are that which are identifiable functions themselves.

The corresponding IO-equations are

$$ny_1y_1''' + (-ny_1' + y_1(by_1 + n(a + \nu)))y_1'' - n(a + \nu)y_1'^2 + by_1^2(a + \nu)y_1' + ab\nu y_1^3, \\ y_2 - n$$

with $\mathbb{K} = \mathbb{C}(n, b, h_1 := a + \nu, h_2 := a\nu)$ as the field of identifiable functions.

Given an ODE-system Σ with the IO-equations \mathcal{S} and the field of identifiable functions $\mathbb{C}(\mathbf{h}(\mathbf{c}))$, we seek for another realization Σ_0 of \mathcal{S} over $\mathbb{C}(\mathbf{h})$. Thus, \mathbf{h} can then be used as a **new set of parameters** that are **identifiable** and Σ_0 replaces Σ as model.

The parametrization corresponding to Σ is

$$P = \left(I, \nu E - aI, \frac{b\nu SI - a\nu E - n\nu^2 E + a^2 nI}{n}, \right. \\ \left. \frac{bn\nu^2 SE - b^2\nu SI^2 - 2abn\nu SI - bn\nu^2 SI + a^2 n^2\nu E + an^2\nu^2 E + n^2\nu^3 E - a^3 n^2 I}{n^2}, n \right).$$

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a is a root of the polynomial

$$X^2 - (a + \nu)X + a\nu \in \mathbb{K}[X].$$

We substitute

$$S = z_{1,0} + a z_{1,1}, E = z_{2,0} + a z_{2,1}, I = z_{3,0} + a z_{3,1}$$

into P , expand, and set the coefficients of a to zero. The resulting variety (called **witness variety**) is given by

$$W := \mathbb{V}(z_{1,0}, z_{3,1}, z_{3,0} + z_{2,0}) \cup \mathbb{V}(z_{2,0}, z_{2,1}, z_{3,0}, z_{3,1}).$$

W has the birational parametrization

$$\phi = (0, z_1, -z_3, z_2, z_3, 0).$$

Then the resulting change of variables

$$\begin{cases} S = az_1, \\ E = -z_3 + az_2, \\ I = z_3, \end{cases}$$

leads to the equivalent system (over $\mathbb{C}(n, b, h_1 = a + \nu, h_2 = a\nu)$)

$$\Sigma_0 = \begin{cases} z_1'(t) = -\frac{bz_1(t)I(t)}{n}, \\ z_2'(t) = -\frac{I(t)(n-bz_1(t))}{n}, \\ I'(t) = a\nu z_2(t) - (a + \nu)I(t) = h_2 z_2(t) - h_1 I(t), \\ y_1(t) = I(t), \\ y_2(t) = n. \end{cases}$$

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Consequently, if there is just one parameter c in a given ODE system Σ , then there is an equivalent realization Σ_0 in an identifiable parameter $h(c)$.

Example 4

Let $F = a_2 y_0^2 + y_1^2 - a_1^2$.

$$P = \left(\frac{a_1}{\sqrt{a_2}} \cdot \frac{1-x^2}{1+x^2}, \frac{2a_1x}{1+x^2} \right) \in \mathbb{Q}(a_1, \sqrt{a_2})(x)^2$$

is a rational parametrization of $\mathbb{V}(F)$. By elementary reasoning it can be shown that $\mathbb{V}(F)$ cannot be parametrized over $\mathbb{Q}(a_1, a_2)$.

Example 4

$$\Sigma = \begin{cases} x' = -c_2(1 + x^2)/2, \\ y = \frac{c_1}{c_2} \cdot \frac{1-x^2}{1+x^2} \end{cases}$$

has for $c_1 = a_1, c_2 = a_2^2$ the corresponding parametrization P . The IO-equation

$$F = c_2^2 y_0^2 + y_1^2 - c_1^2$$

has the identifiable functions $h_1 = c_1^2, h_2 = c_2^2$. Since there is no rational parametrization of $\mathbb{V}(F)$ with coefficients in $\mathbb{C}(h_1, h_2)$, there is **no realization** equivalent to Σ with just **identifiable parameters**.

Witness variety

Assume that the ODE system $\Sigma = \{\mathbf{x}' = \mathbf{f}(\mathbf{u}, \mathbf{x}), \mathbf{y} = \mathbf{g}(\mathbf{u}, \mathbf{x})\}$ with corresponding rational parametrization P has a coefficient field that is algebraic over $\mathbb{C}(\mathbf{h})$ of degree n , where \mathbf{h} are the identifiable functions. Substitute each x_i by

$$x_i = z_{i,0} + z_{i,1}\alpha + \cdots + z_{i,m-1}\alpha^{m-1},$$

where $z_{i,j}$ are new variables and α is the primitive element of the algebraic field extension. Write

$$P = \left(\sum_{j=0}^{m-1} \frac{H_{1,j}(\mathbf{z})}{\delta(\mathbf{z})} \alpha^j, \dots, \sum_{j=0}^{m-1} \frac{H_{n,j}(\mathbf{z})}{\delta(\mathbf{z})} \alpha^j \right).$$

Define the **witness variety** W (associated to P and α) as the Zariski closure of $\mathbb{V}(\{H_{i,j}(\mathbf{z})\}_{1 \leq i \leq n, 1 \leq j \leq m-1}) \setminus \mathbb{V}(\delta(\mathbf{z}))$.

Identifiable functions

Assume that W has a component of dimension $\dim(\mathbb{V}(\mathcal{S}))$ with a birational parametrization $(s_0, \dots, s_{n-1}) \in \mathbb{C}(\mathbf{h})(\mathbf{z})^n$. Then we can use the reparametrization

$$s = s_0(\mathbf{z}) + \dots + s_{n-1}(\mathbf{z}) \cdot \alpha^{n-1}$$

to obtain the realization

$$\Sigma_0 = \begin{cases} \mathbf{z}' = \mathcal{J}(\mathbf{s})^{-1} \cdot \mathbf{f}(\mathbf{u}, \mathbf{s}), \\ \mathbf{y} = \mathbf{g}(\mathbf{u}, \mathbf{s}). \end{cases}$$

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- 1 In the case of $\dim(\mathbb{V}(\mathcal{S})) = 1$, the existence of such a birational parametrization is **equivalent** to W having a component that is a **hypercircle** parametrizable over $\mathbb{C}(\mathbf{c})$.
- 2 If P and the reparametrization are assumed to be **polynomial**, then W has to have a component that is a **line** (over $\mathbb{C}(\mathbf{c})$).

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